



S-parameter approximation using rational function

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Introduction

- Electrical circuits operating at high frequency
- Component size comparable with wavelengths
- Simulation using lumped elements – netlists with high number of discrete components
- Transmission line behaviour of interconnects
- Skin effect
- Dispersion

SIMULATION CHALLENGE

Simulation using the transfer function

- Defined in the frequency domain
- 1-port networks have impedance or admittance transfer functions
- N-port networks are represented with impedance or admittance **matrix**
- Impedance or admittance measurement are unusable at high frequencies: problem of defining short circuits (parasitic inductance) and open end (parasitic capacitance)
- High frequency characterization are obtained using the S-parameters

Passive devices modelling at high frequencies

- Connectors, interconnects, transmission lines
- Model must retain passive behaviour
- Passive models involve following characteristics:
 1. Causality
 2. Stability
 3. Passivity
- This work considers modelling in the frequency domain

Causality in the frequency domain

- Causal impulse response satisfy:

$$h(t) = \text{sign}(t)h(t) \quad \text{sign}(t) = \begin{cases} -1 & t < 0 \\ 0 & t = 0 \\ 1 & t > 0 \end{cases} \quad F\{\text{sign}(t)\} = \frac{2}{j\omega}$$

$$F\{h(t)\} = \frac{1}{2\pi} F\{\text{sign}(t)\} * F\{h(t)\}$$

$$H(j\omega) = \frac{1}{j\pi} \text{pv} \int_{-\infty}^{+\infty} \frac{H(j\omega')}{\omega - \omega'} d\omega'$$

$$H(j\omega) = U(j\omega) + jV(j\omega)$$

$$U(\omega) = \frac{1}{\pi} \text{pv} \int_{-\infty}^{+\infty} \frac{V(\omega')}{\omega - \omega'} d\omega'$$

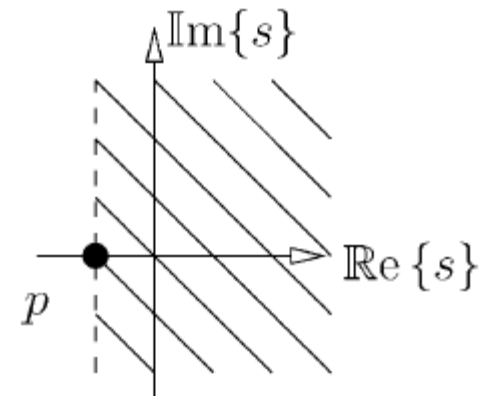
$$V(\omega) = -\frac{1}{\pi} \text{pv} \int_{-\infty}^{+\infty} \frac{U(\omega')}{\omega - \omega'} d\omega'$$

Dispersion relations

Stability in the frequency domain

- Impulse responses of unstable systems don't have Fourier transform
- Closely related is the Laplace transform. The region of convergence doesn't include the imaginary axis for unstable systems
- To analyze unstable systems Laplace transform is needed for frequency domain (more precise complex frequency domain)
- Example

$$h_1(t) = e^{pt}S(t) \quad H_1(s) = \frac{1}{s - p} \quad PK: \operatorname{Re}\{s\} > p$$



Passivity in the frequency domain

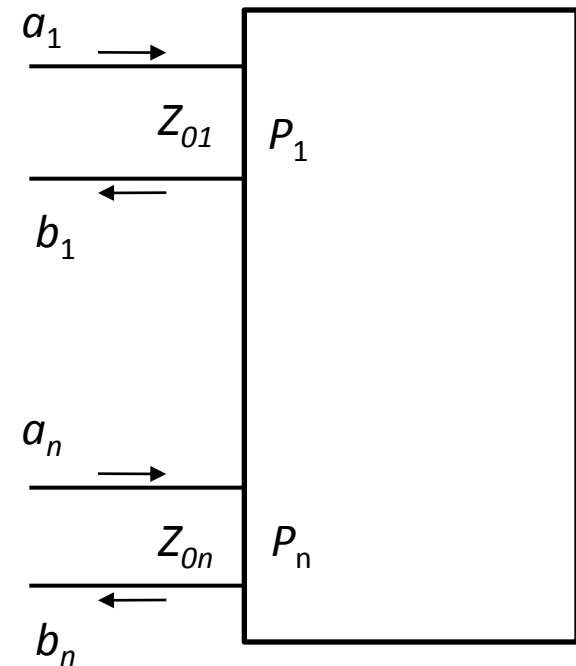
For any frequency the passivity requirement relates the input and output power

$$\sum_{i=1}^n (|a_i|^2 - |b_i|^2) \geq 0$$

$$a^H a - b^H b \geq 0$$

$$a^H a - S^H a^H S a \geq 0$$

$$a^H (I - S^H S) a \geq 0$$



Recapitulation of passivity requirements in the frequency domain

$\mathbf{S}(j\omega)$ matrix represents a passive network if the following is satisfied:

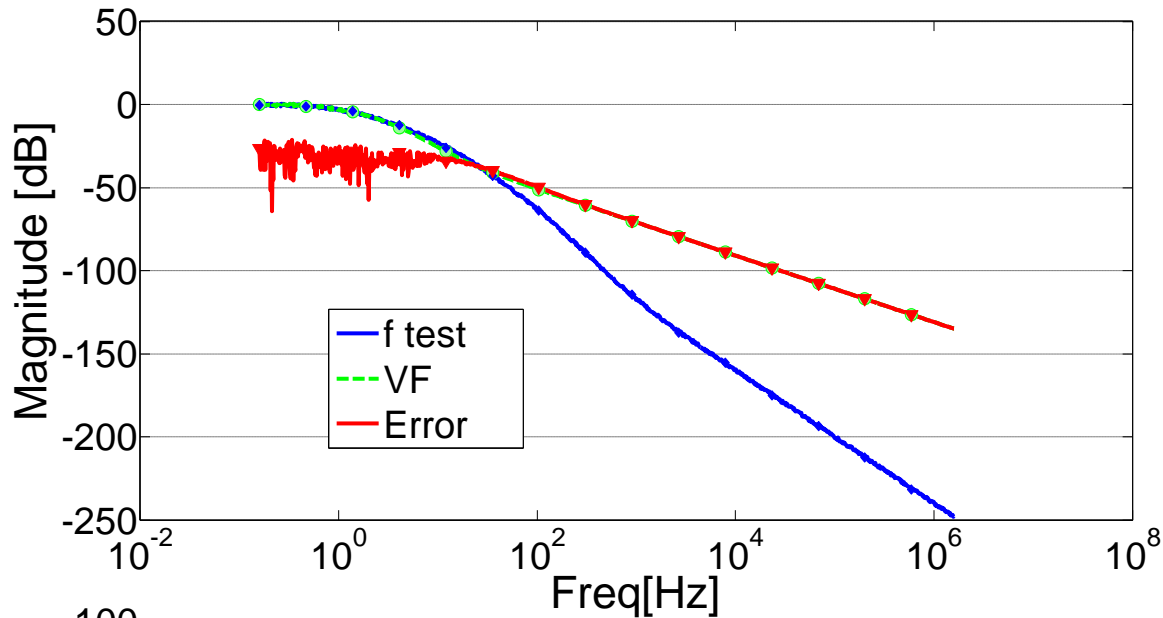
- 1) Dispersion relation hold
- 2) $\mathbf{I} - \mathbf{S}^H(j\omega) \mathbf{S}(j\omega)$ is positive semidefinite for all ω
- 3) Fourier transform of the impulse response exist (obviously satisfied always when S-parameter characteristic is given and the 2nd requirement hold)
- 4) $\mathbf{S}(-j\omega) = \mathbf{S}^*(j\omega)$ (time domain impulse response is purely real without imaginary, which is practically always the case)

S-parameter approximated using the rational function

- Linear systems have rational transfer functions
- All of the passivity criteria (EXCEPT one) is already “built in” by choosing the rational basis function for approximation
- Rational function models are represented as: state space, pole-zero, residue-pole, etc.
- Algorithm for rational approximation: VECTOR FITTING (VF)
- Widely used algorithm for rational modelling
- Based on iteratively solving least squares which is a mature and reliable technology
- All poles are fixed in the left complex plane by VF

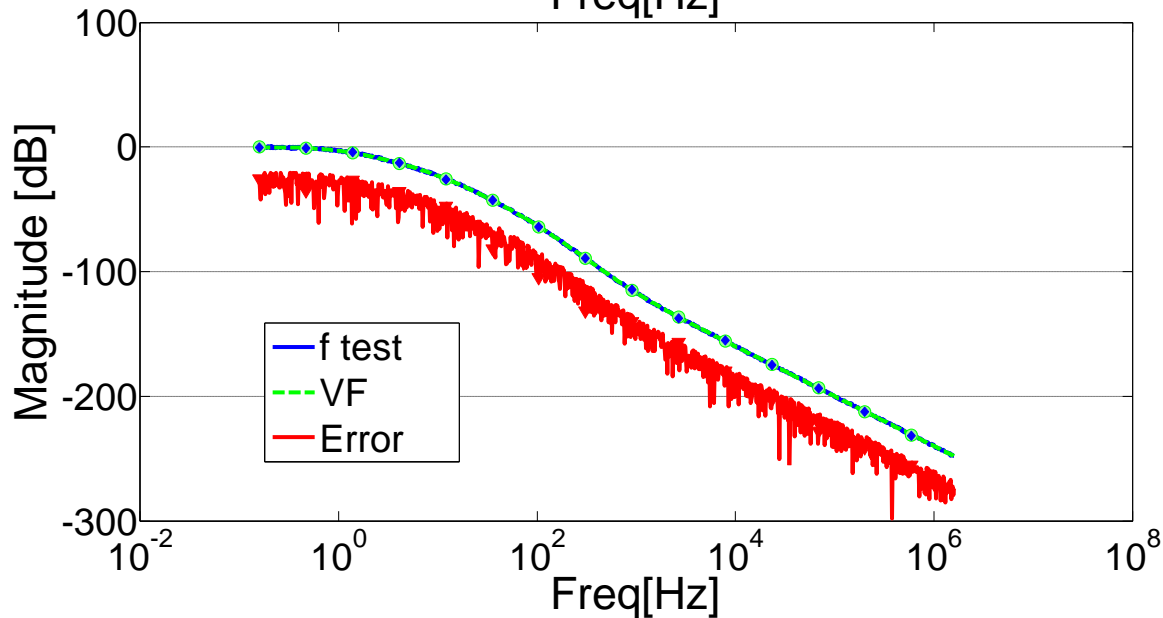
VF algorithm

- The name comes from the possibility of fitting a number of different functions (vector of functions) with the common set of poles
- Least squares equations are solved using the powerful Matlab 'backslash' operator
- SVD least squares solving can easily be added as the most numerically most reliable method but it is too expensive in terms of time with no improvement in accuracy
- Variety of improved basic VF algorithms exist:
- Standard (VF), relaxed (RVF), orthonormal VF (OVF), adding and skimming (VF-AS), recursive VF (RecVF)
- All versions implemented in Matlab



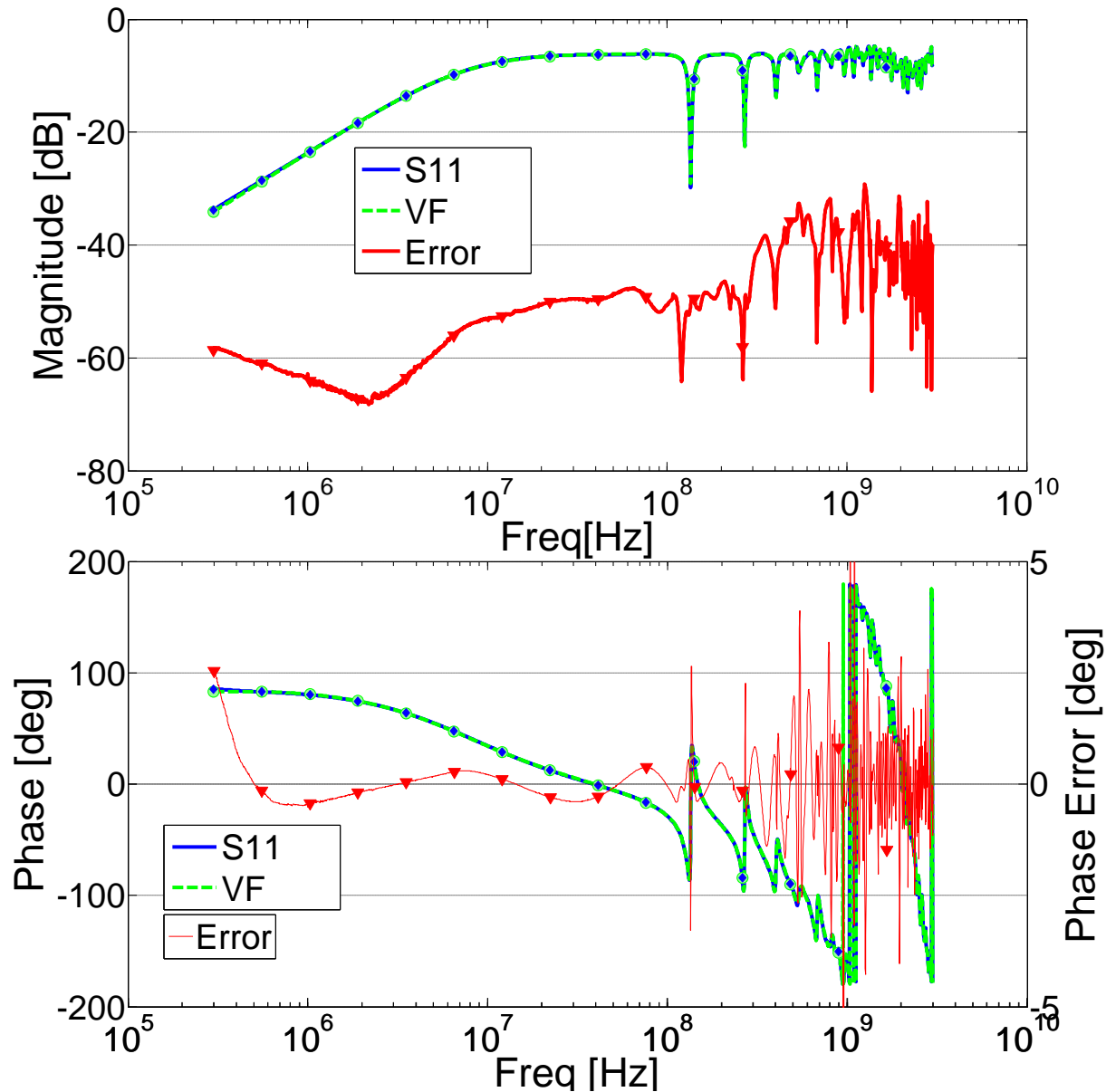
Test function:
 -5 poles
 -dynamic range 250 db

non weighted VF
 -60 poles model
 results

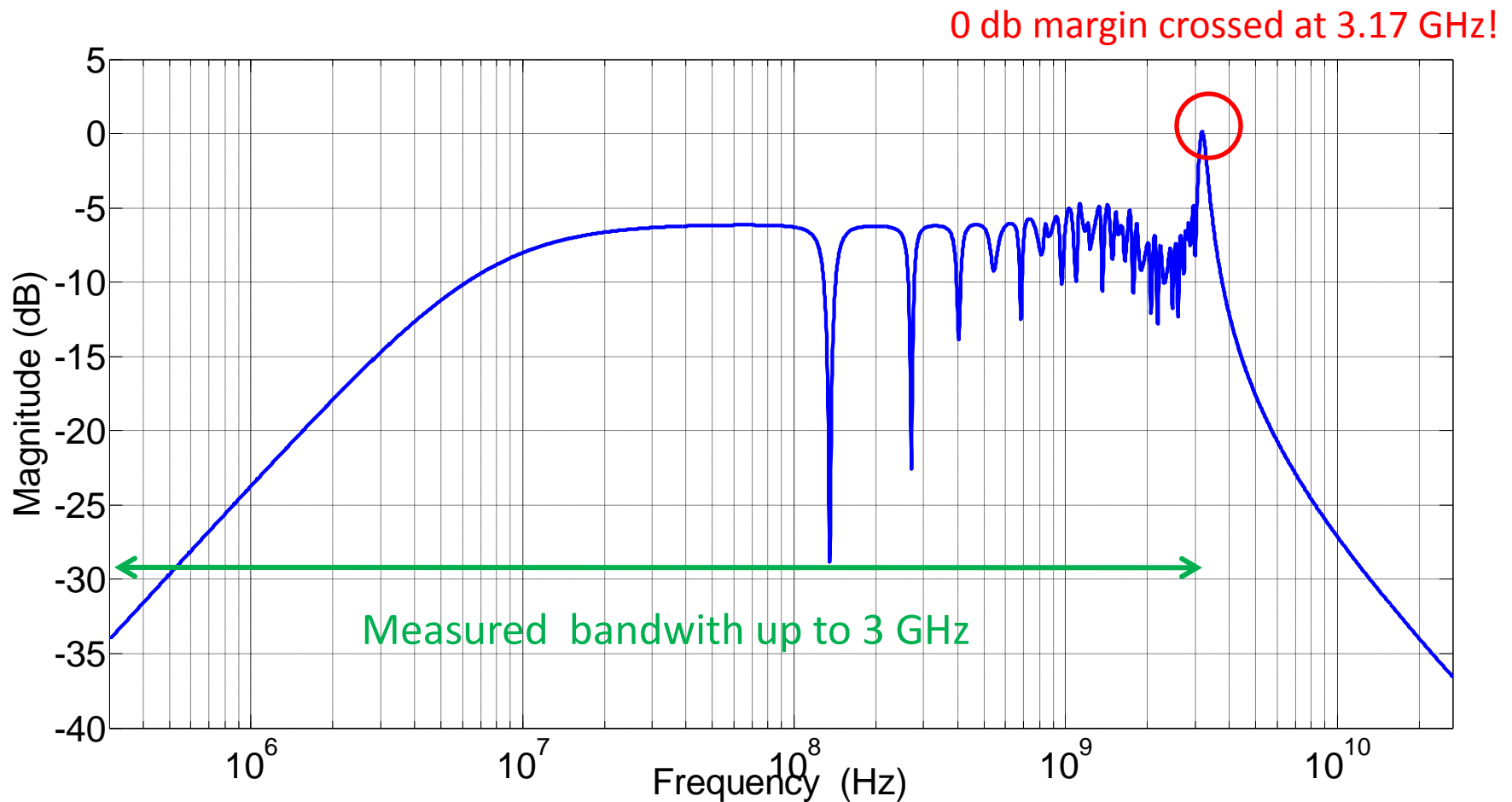


weighted VF
 -5 poles results!
 -20dB margin in the whole
 modelling band
 weighting

S-parameter cable modelling 300kHz-3GHz using 60 poles



S-parameter cable modelling 300kHz-3GHz using 60 poles



Global passivity of the model

- passivity must be achieved for all frequencies
- $I - S^H(j\omega) S(j\omega)$ is psd for all ω
- Rational model achieve zero magnitude at $\omega=\infty$ by construction
- Critical region is the band beyond the modelling bandwidth
- This is the main focus for the future work