

# **Lossless Image Compression Based on Contextual Adaptation of Predictor Blends**

**First Croatian Computer Vision Workshop 2012**

Josip Knežović, Martin Žagar, Mario Kovač  
Faculty of Electrical Engineering and Computing  
University of Zagreb, Croatia

[josip.knezovic@fer.hr](mailto:josip.knezovic@fer.hr)

Zagreb, Croatia, 2012

## CBPC – Contents

- CBPC – Contents
- Introduction
- CBP predictor
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

- Introduction
- CBP predictor
- Results
- Conclusion

# Introduction

Predictive image coding:

1. Prediction  $\hat{I} = f(\Omega(I))$
2. Contextual probability model
3. Entropy coding

# Introduction

Predictive image coding:

1. Prediction  $\hat{I} = f(\Omega(I))$
2. Contextual probability model
3. Entropy coding

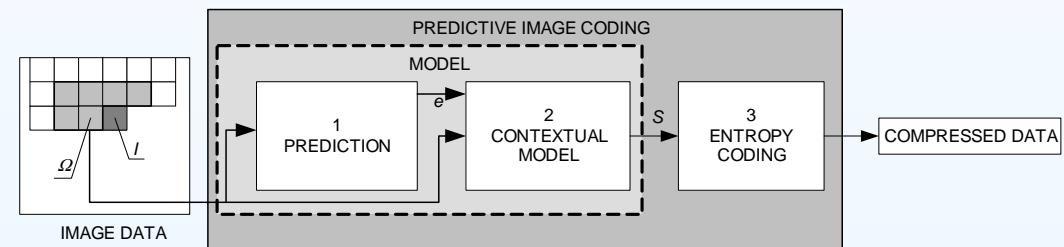
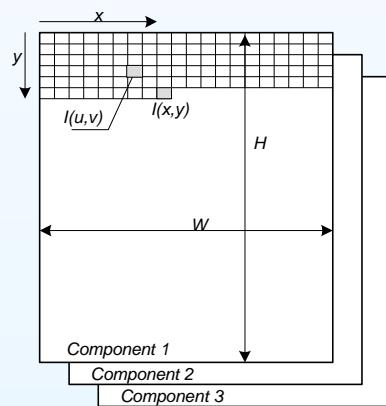


Figure 1: Predictive image coding

$$\hat{I}(x, y) = f(\Omega(x, y)) = \sum_{I(i,j) \in \Omega} a_{i,j} \cdot I(i, j)$$

$$e(x, y) = I(x, y) - \hat{I}(x, y)$$

# CBP predictor

- CBPC – Contents
- Introduction
- **CBP predictor**
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

Typical image regions:

- CBPC – Contents
- Introduction
- **CBP predictor**
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

## CBP predictor

Typical image regions:

- Smooth regions:  $\sum a_{i,j} = 1$

- CBPC – Contents
- Introduction
- **CBP predictor**
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

## CBP predictor

Typical image regions:

- Smooth regions:  $\sum a_{i,j} = 1$
- Planar regions: at least one  $a_{i,j} < 0$

- CBPC – Contents
- Introduction
- **CBP predictor**
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

## CBP predictor

Typical image regions:

- Smooth regions:  $\sum a_{i,j} = 1$
- Planar regions: at least one  $a_{i,j} < 0$
- Noisy regions:  $\sum |a_{i,j}| \rightarrow 0$

- CBPC – Contents
- Introduction
- **CBP predictor**
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

## CBP predictor

Typical image regions:

- Smooth regions:  $\sum a_{i,j} = 1$
- Planar regions: at least one  $a_{i,j} < 0$
- Noisy regions:  $\sum |a_{i,j}| \rightarrow 0$
- Edges and textures: Most important visual part - adaptation mechanism

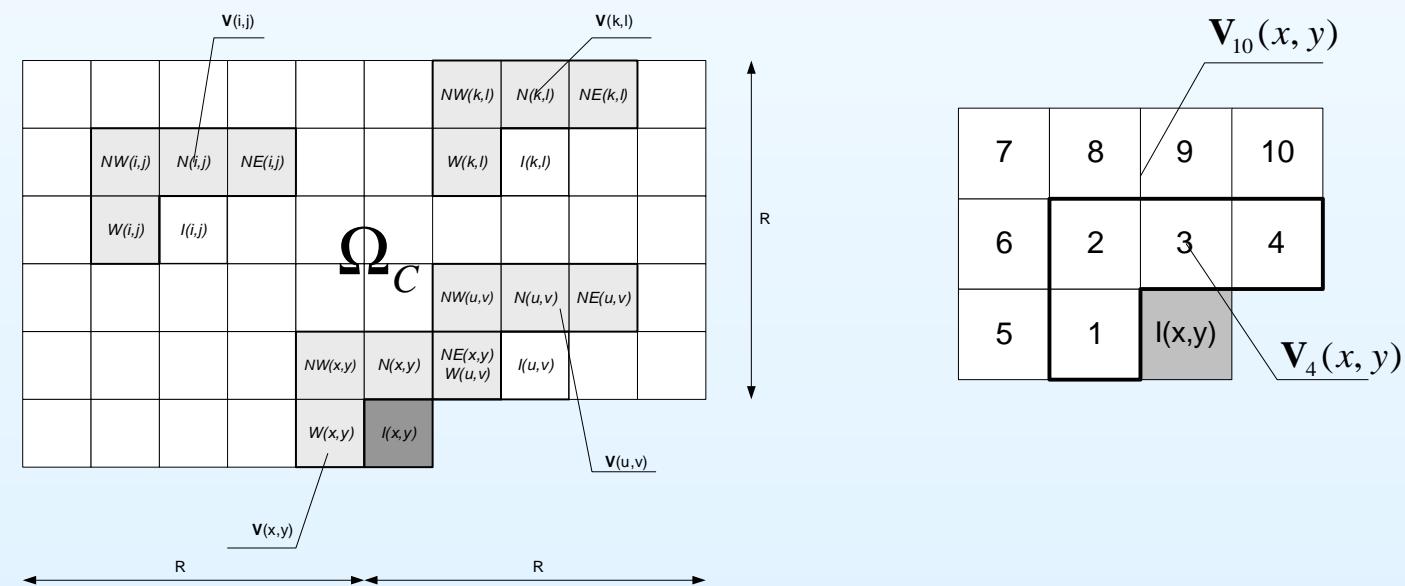
- CBPC – Contents
- Introduction
- **CBP predictor**
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

## CBP predictor

Typical image regions:

- Smooth regions:  $\sum a_{i,j} = 1$
- Planar regions: at least one  $a_{i,j} < 0$
- Noisy regions:  $\sum |a_{i,j}| \rightarrow 0$
- Edges and textures: Most important visual part - adaptation mechanism

Proposed predictor: *Classification and Blending Predictor – CBP*



# CBP predictor

## CBP predictor

$\forall I(i, j) \in \Omega_C \rightarrow v(i, j)$ . Set of static predictors:  $\mathcal{F} = \{f_1, f_2, \dots, f_N\}$ .

## CBP predictor

$\forall I(i, j) \in \Omega_C \rightarrow v(i, j)$ . Set of static predictors:  $\mathcal{F} = \{f_1, f_2, \dots, f_N\}$ .

### 1. Classification:

$$D(i, j) = \|v(i, j) - v(x, y)\| = \|w - v\| = \sum_{k=1}^d |w_k - v_k|^2$$

Find  $M$  pixels with the smallest distances to the current pixel's vector  
 $v(x, y)$  = *Current cell*  $\Omega_B$ .

## CBP predictor

$\forall I(i, j) \in \Omega_C \rightarrow v(i, j)$ . Set of static predictors:  $\mathcal{F} = \{f_1, f_2, \dots, f_N\}$ .

### 1. Classification:

$$D(i, j) = \|v(i, j) - v(x, y)\| = \|w - v\| = \sum_{k=1}^d |w_k - v_k|^2$$

Find  $M$  pixels with the smallest distances to the current pixel's vector  
 $v(x, y)$  = *Current cell*  $\Omega_B$ .

### 2. Blending: For every $f_k \in \mathcal{F}$ determine penalty term $G_k$

$$G_k = \frac{1}{M} \sum_{I(i, j) \in \Omega_B} (f_k(i, j) - I(i, j))^2 \quad \forall f_k \in \mathcal{F}$$

## CBP predictor

$\forall I(i, j) \in \Omega_C \rightarrow v(i, j)$ . Set of static predictors:  $\mathcal{F} = \{f_1, f_2, \dots, f_N\}$ .

### 1. Classification:

$$D(i, j) = \|v(i, j) - v(x, y)\| = \|w - v\| = \sum_{k=1}^d |w_k - v_k|^2$$

Find  $M$  pixels with the smallest distances to the current pixel's vector  
 $v(x, y)$  = *Current cell*  $\Omega_B$ .

### 2. Blending: For every $f_k \in \mathcal{F}$ determine penalty term $G_k$

$$G_k = \frac{1}{M} \sum_{I(i, j) \in \Omega_B} (f_k(i, j) - I(i, j))^2 \quad \forall f_k \in \mathcal{F}$$

### 3. Prediction:

$$\hat{I}(x, y) = F(x, y) = \left[ \frac{\left( \sum_{k=1}^N \frac{1}{G_k} \cdot \hat{I}_k(x, y) \right)}{\sum_{k=1}^N 1/G_k} \right]$$

## CBP predictor

$\forall I(i, j) \in \Omega_C \rightarrow v(i, j)$ . Set of static predictors:  $\mathcal{F} = \{f_1, f_2, \dots, f_N\}$ .

### 1. Classification:

$$D(i, j) = \|v(i, j) - v(x, y)\| = \|w - v\| = \sum_{k=1}^d |w_k - v_k|^2$$

Find  $M$  pixels with the smallest distances to the current pixel's vector  
 $v(x, y)$  = *Current cell*  $\Omega_B$ .

### 2. Blending: For every $f_k \in \mathcal{F}$ determine penalty term $G_k$

$$G_k = \frac{1}{M} \sum_{I(i, j) \in \Omega_B} (f_k(i, j) - I(i, j))^2 \quad \forall f_k \in \mathcal{F}$$

### 3. Prediction:

$$\hat{I}(x, y) = F(x, y) = \left[ \frac{\left( \sum_{k=1}^N \frac{1}{G_k} \cdot \hat{I}_k(x, y) \right)}{\sum_{k=1}^N 1/G_k} \right]$$

### 4. Error correction:

$$\bar{e}(\Omega_B) = \frac{1}{M} \sum_{I \in \Omega_B} (F(i, j) - I(i, j))$$

$$\dot{I}(x, y) = \hat{I}(x, y) + e(\bar{\Omega}_B)$$

## CBP parameters

- Radius  $R$
- Cell population  $M$
- Vector size  $d$  (Set to 5).
- Set of predictors  $\mathcal{F} = \{f_N, f_W, f_{NW}, f_{NE}, f_{GW}, f_{GN}, f_{PL}\}$

$$f_N = I(x, y - 1)$$

$$f_{NW} = I(x - 1, y - 1)$$

$$f_{GW} = 2 \cdot I(x, y - 1) - I(x, y - 2)$$

$$f_W = I(x - 1, y)$$

$$f_{NE} = I(x + 1, y - 1)$$

$$f_{GN} = 2 \cdot I(x - 1, y) - I(x - 2, y)$$

$$f_{PL} = I(x, y - 1) + I(x - 1, y) - I(x - 1, y - 1)$$

Selected settings for CBP predictor

Radius $R$	Population $M$	Vector size $d$
5	7	4

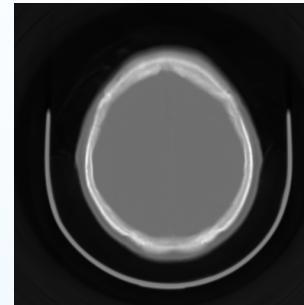
# Test images



(a) CR-chest



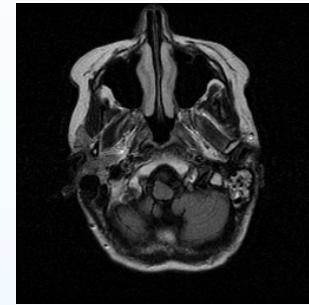
(b) CT-abdo



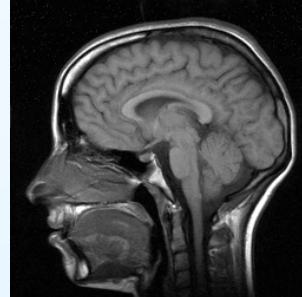
(c) CT-brain



(d) CT-lomb



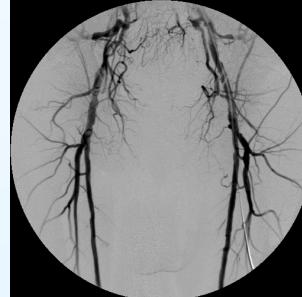
(e) MR-head



(f) MR-head1



(g) MR-knee



(h) OT-an7



(i) OT-colon

# CBPC Results

- CBPC – Contents
- Introduction
- CBP predictor
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

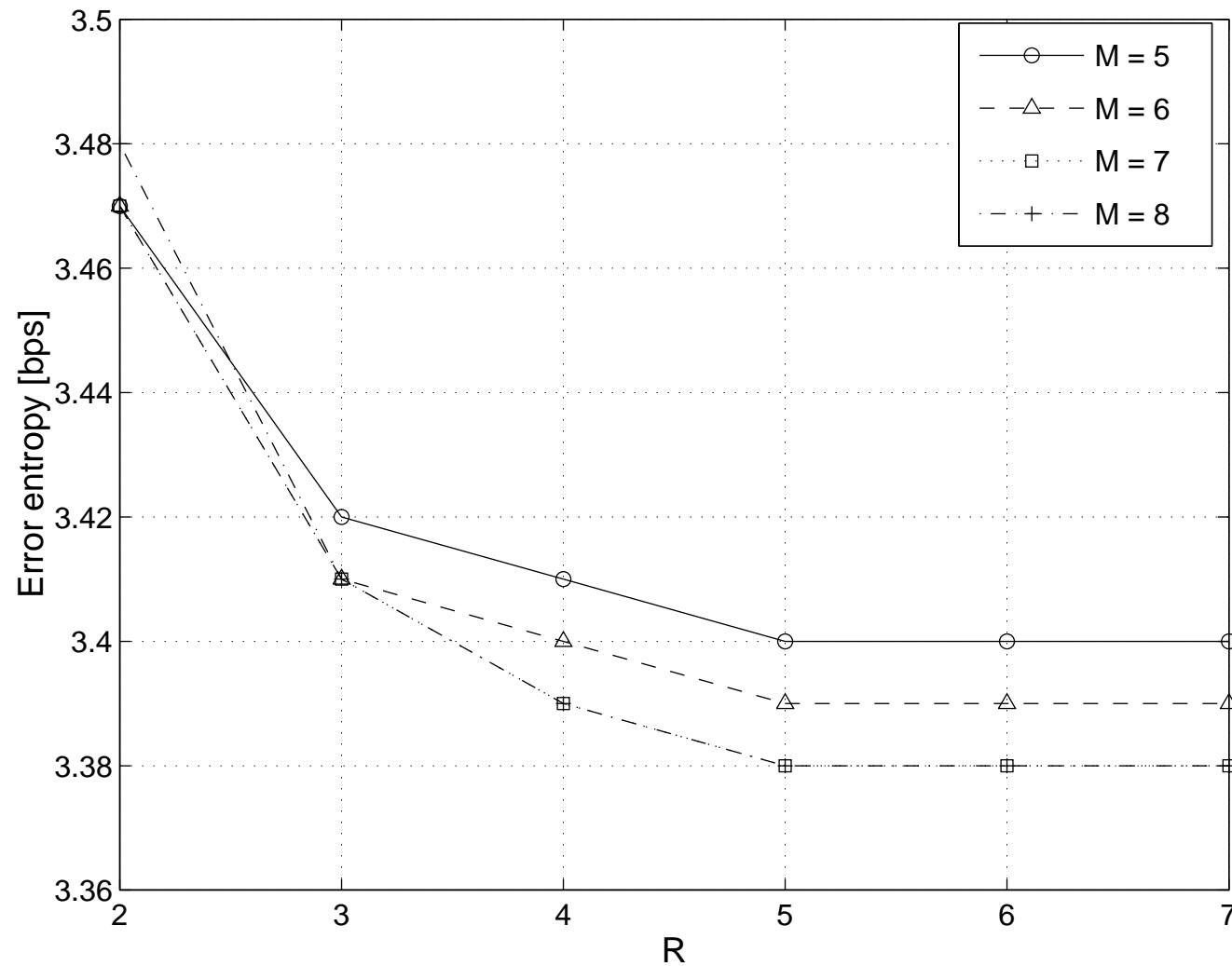


Figure 2: Average zero-order entropy vs. radius  $R$

# CBP Results

- CBPC – Contents
- Introduction
- CBP predictor
- CBP parameters
- Test images
- **CBPC Results**
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

Zero-order entropy of the prediction error (bps)

Image	MED	GAP	CBP
CR-chest	2.52	2.49	<b>2.28</b>
CT-abdo	2.67	2.73	<b>2.72</b>
CT-brain	1.79	1.93	<b>1.17</b>
CT-lomb	2.46	2.59	<b>2.19</b>
MR-head	4.80	4.75	<b>4.55</b>
MR-head1	4.85	4.82	<b>4.51</b>
MR-knee	5.24	5.20	<b>5.12</b>
OT-an7	4.20	4.28	<b>4.17</b>
OT-colon	3.84	3.91	<b>3.75</b>
<b>Average</b>	3.60	3.63	<b>3.38</b>

- CBPC – Contents
- Introduction
- CBP predictor
- CBP parameters
- Test images
- **CBPC Results**
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System

## CBPC Results

Contextual model from CALIC algorithm (Ref. [4] in the article.)

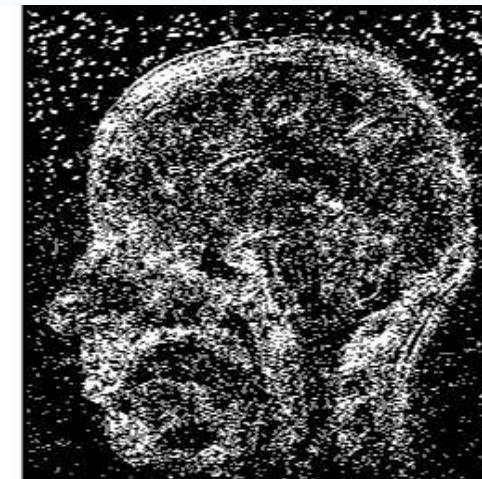
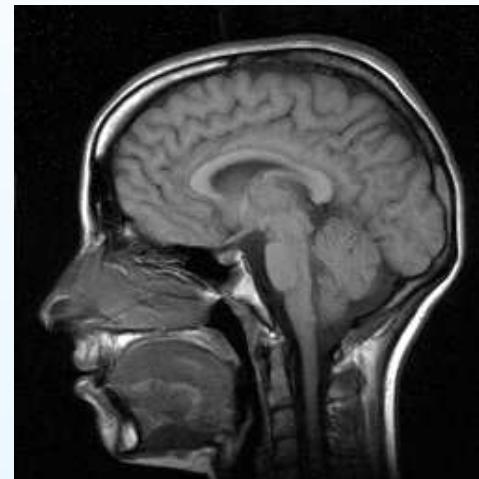
Bit-rate of a complete coder (bps)

Image	CALIC	JPEG-LS	JPEG2000R	<b>CBPC</b>
CR-chest	2.35	2.39	2.52	<b>2.27</b>
CT-abdo	2.27	1.89	2.59	<b>1.92</b>
CT-brain	1.24	1.29	1.42	<b>1.10</b>
CT-lomb	2.21	2.34	2.38	<b>2.17</b>
MR-head	4.27	4.44	4.47	<b>4.18</b>
MR-head1	4.44	4.62	4.71	<b>4.33</b>
MR-knee	4.98	5.08	5.11	<b>4.92</b>
OT-an7	3.70	3.67	3.97	<b>3.62</b>
OT-colon	3.21	3.20	3.45	<b>3.10</b>
<b>Average</b>	<b>3.18</b>	<b>3.21</b>	<b>3.40</b>	<b>3.07</b>

# SCBPC Selective Computation

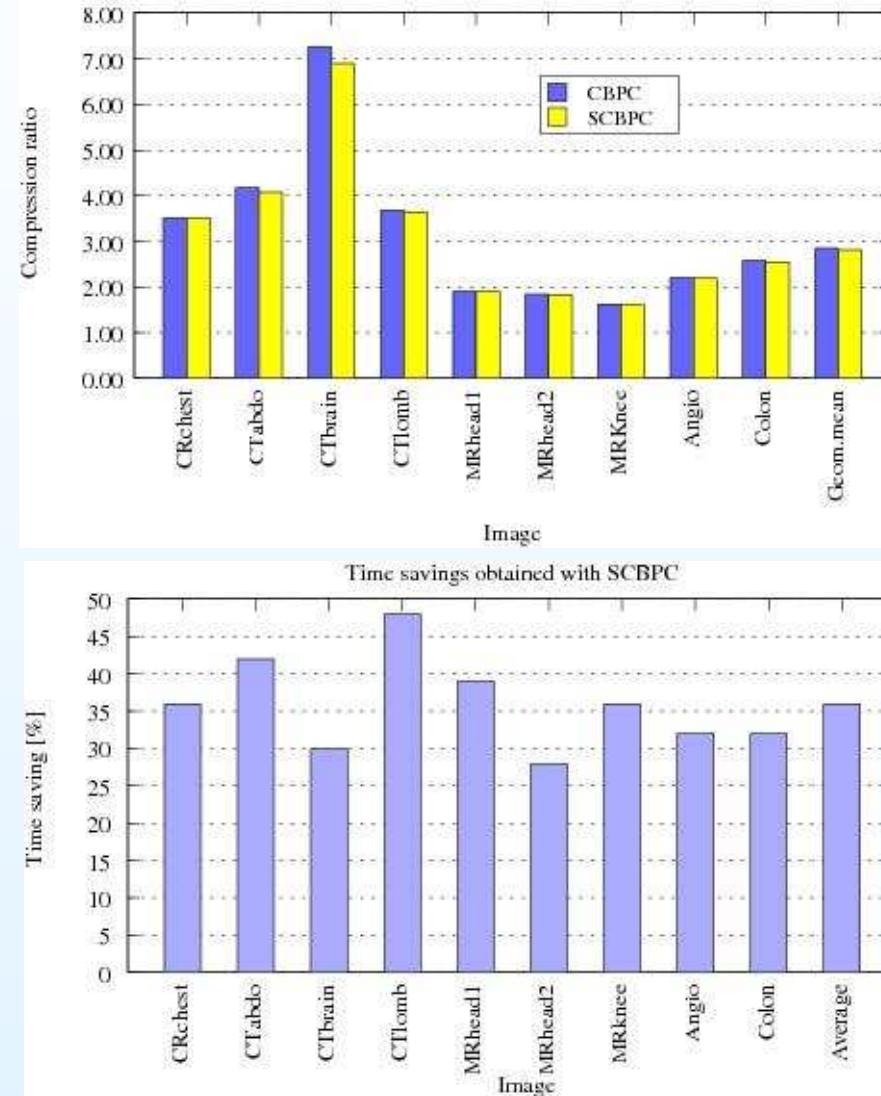
- CBPC – Contents
- Introduction
- CBP predictor
- CBP parameters
- Test images
- CBPC Results
- **SCBPC Selective Computation**
- SCBPC Performance Results
- Software System

1. Reduce the number of penalty computation
2. Threshold T for penalty recomputation



# SCBPC Performance Results

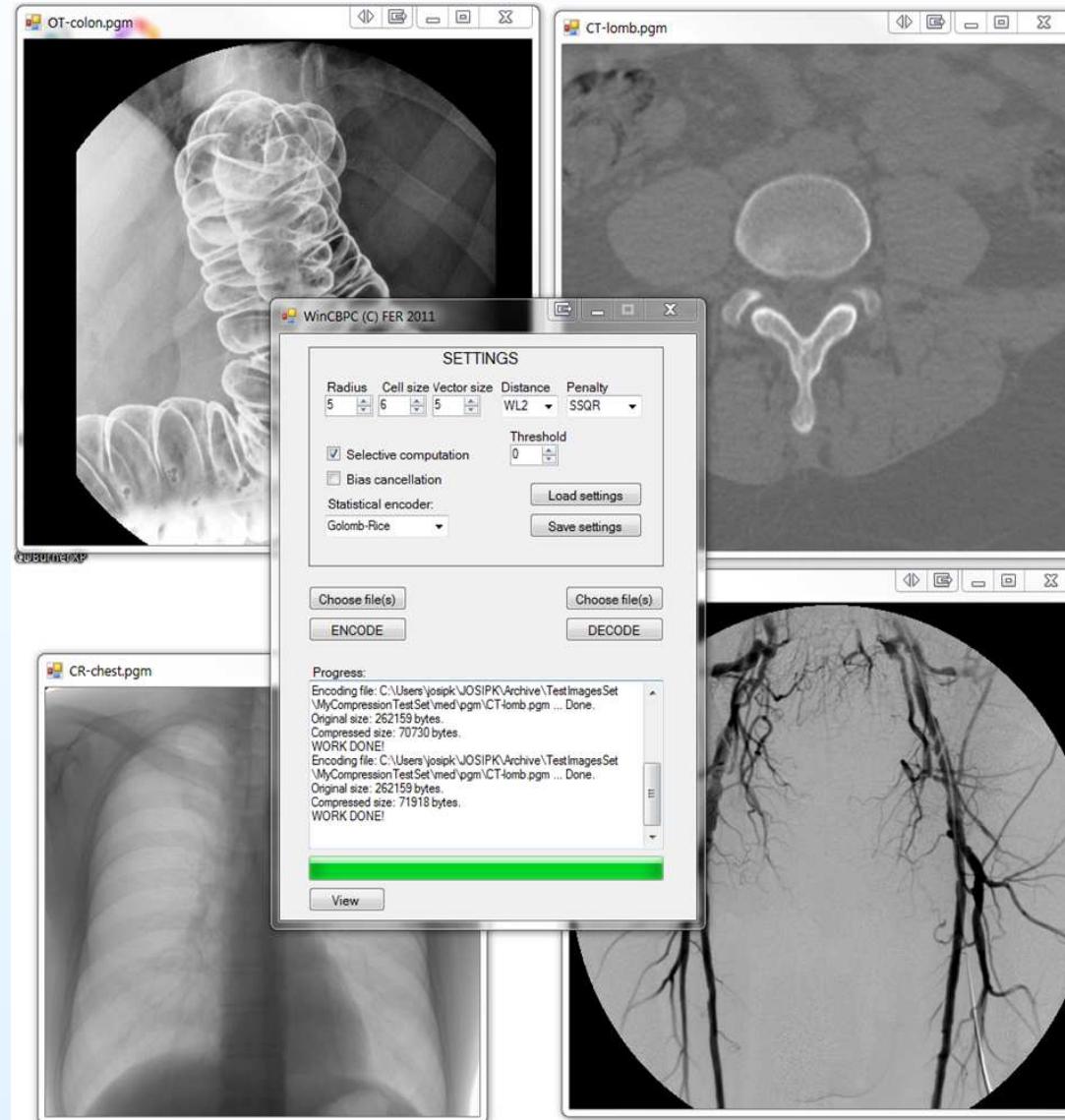
- CBPC – Contents
- Introduction
- CBP predictor
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results
- Software System



# Software System

- CBPC – Contents
- Introduction
- CBP predictor
- CBP parameters
- Test images
- CBPC Results
- SCBPC Selective Computation
- SCBPC Performance Results

## ● Software System



THANK YOU!